(Somewhat) Advanced Hierarchical Models

Ben Goodrich

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Obligatory Disclosure

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- Ben is also a manager of GG Statistics LLC, which utilizes Stan for business purposes
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Goals for the Tutorial

- Yesterday, we talked a lot about models where the probability distribution for some variable depends on another variable
- Today, we are going to talk about the case where probability distribution for some parameter depends on another parameter
- Richard McElreath argues that these hierarchical models should be the default approach to modeling
- Learn about how to estimate hierarchical models with the rstanarm and brms R packages

Hierarchical Models

- A hierarchical model is one where a prior is specified on a parameter conditional on another unknown parameter
- Hierarchical models are often used in situations to allow parameters to vary by categorical group
- Suppose there are J groups & N_i observations in jth group
- Best way to think about such structures:
 - There is a likelihood contribution for the jth group
 - There are priors over how parameters vary across groups
 - There are priors on parameters common to all groups
- Relevant prior information pertains to how similar you believe the groups' data-generating processes to be

School Example

This is a data-generated process we talked about yesterday:

$$au \sim \operatorname{Exponential}(r_{\tau})$$
 $lpha_{j} \sim \mathcal{N}(0, \tau) \, \forall j \, [\text{hierarchical}]$
 $\beta \sim \mathcal{N}(\mu_{\beta}, \sigma_{\beta})$
 $\sigma \sim \operatorname{Exponential}(r_{\sigma})$
 $\varepsilon_{ij} \sim \mathcal{N}(0, \sigma)$
 $y_{ij} \equiv \alpha_{j} + \beta \times \operatorname{class_size}_{i} + \varepsilon_{ij} \, \forall i, j$

Stan Function for School Example

```
vector cluster_DGP_rnq(int J, int[] N, vector class_size,
                       real r_tau, real r_sigma,
                       real mu_beta, real sigma_beta) {
  real tau = exponential_rng(r_tau);
  real sigma = exponential_rng(r_sigma);
  real beta = normal_rng(mu_beta, sigma_beta);
  vector[sum(N)] v;
  int pos = 1;
  for (j in 1:J) {
    real alpha_j = normal_rng(0, tau);
    for (i in 1:N[j]) {
      real mu = alpha_j + beta * class_size[pos];
      y[pos] = mu + normal_rng(0, sigma);
      pos += 1;
  return v;
```

Restatement of the Hierarchical Linear Model

- · Generally, both intercepts & slopes can vary across groups
- Let $\boldsymbol{\beta}_j = \boldsymbol{\beta} + \mathbf{b}_j$ and $\mathbf{b}^\top = \begin{bmatrix} \mathbf{b}_1^\top & \mathbf{b}_2^\top & \cdots & \mathbf{b}_J^\top \end{bmatrix}$. Rewrite the model as $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{b} + \boldsymbol{\varepsilon}$ where \mathbf{Z} is a sparse matrix that basically interacts \mathbf{X} with group-specific dummy variables.
- Bayesians: $\mathbf{b} \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma}(\boldsymbol{\theta}))$ and $\mathbf{y} \sim \mathcal{N}(\mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{b}, \sigma^2\mathbf{I})$
- For frequentists, each \mathbf{b}_j is not a fixed "parameter" but rather a random variable that is part of the error term
- Frequentists integrate out each \mathbf{b}_j and then choose $\widehat{\boldsymbol{\beta}}, \widehat{\sigma}$, and $\mathbf{\Sigma}\left(\widehat{\boldsymbol{\theta}}\right)$ to maximize $\mathbf{y} \sim \mathcal{N}\left(\mathbf{X}\boldsymbol{\beta}, \sigma^2\mathbf{Z}\mathbf{\Sigma}(\boldsymbol{\theta})\mathbf{Z}^{\top}\right)$
- Technically, $\hat{\mathbf{b}}_j$ is not "estimated" but rather "predicted" from the residuals $\mathbf{e} = \mathbf{v} \mathbf{X}\hat{\boldsymbol{\beta}}$ by subsequently regressing \mathbf{e} on \mathbf{Z}

Table 2 from the **Ime4** Vignette (frequentist)

Formula	Alternative	Meaning
(1 g)	1 + (1 g)	Random intercept with fixed mean
0 + offset(o) + (1 g)	-1 + offset(o) + (1 g)	Random intercept with a priori means
(1 g1/g2)	(1 g1)+(1 g1:g2)	Intercept varying among g1 and g2 within g1
(1 g1)+(1 g2)	1 + (1 g1) + (1 g2)	Intercept varying among g1 and g2
x + (x g)	1 + x + (1 + x g)	Correlated random intercept and slope
x + (x g)	1 + x + (1 g) + (0 + x g)	Uncorrelated random intercept and slope

Table 2: Examples of the right-hand sides of mixed-effects model formulas. The names of grouping factors are denoted $\mathsf{g},\,\mathsf{g1},\,\mathsf{and}\,\mathsf{g2},\,\mathsf{and}\,\mathsf{covariates}$ and a priori known offsets as x and o .

Bayesian Implementations with Ime4 / mgcv Syntax

- The rstanarm and brms packages accept the same | syntax as lme4
- Both also permit the same s (...) syntax as mgcv to use smooth, non-linear functions of parameters
- Add arguments for the priors on α , β , σ , etc.
- Try rstanarm and / or brms first to make sure your data are amenable to a hierarchical model

Tadpole Example from McElreath, chapter 12

```
dim(as.matrix(post)) # raw draws from posterior distribution
## [1] 4000 51
```

Results of Tadpole Example from McElreath

```
## stan_glmer
## family: binomial [logit]
## formula: cbind(surv, density - surv) ~ size + (1 | tank)
## observations: 48
## ----
##
## Estimates:
##
        Median MAD SD
## (Intercept) 1.2 0.4
## sizesmall 0.4 0.5
##
## Error terms:
## Groups Name Std.Dev.
## tank (Intercept) 1.6
## Num. levels: tank 48
##
## Sample avg. posterior predictive
## distribution of y (X = xbar):
## Median MAD SD
## mean_PPD 16.3 0.4
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```

More Results of Tadpole Example from McElreath

```
fixef (post)
## (Intercept) sizesmall
## 1.1787690 0.4306905
NROW (ranef (post) $tank)
## [1] 48
head(cbind(coef(post)$tank[,1],
          fixef(post)[1] + ranef(post)$tank))
##
     coef(post)$tank[, 1] (Intercept)
## 1
                2.040190 2.040190
                2.921214 2.921214
## 2
                0.952524 0.952524
                2,922820 2,922820
## 5
                1.712078 1.712078
                1.713280
                           1.713280
```

A Smooth Nonlinear Model with brms

- The s (roach1) says that the logarithm of the conditional number of roaches is a spline function of the previous number of roaches
- This can also be represented in $\eta = X\beta + Zb$ form
- Simon Wood has a new edition of his book out

Results of Nonlinear Model

```
Family: poisson
 Links: mu = log
Formula: y ~ s(roach1) + treatment
  Data: roaches (Number of observations: 262)
Samples: 4 chains, each with iter = 2000; warmup = 1000; thin = 1
         total post-warmup samples = 4000
   ICs: LOO = NA; WAIC = NA; R2 = NA
Smooth Terms:
```

```
Estimate Est.Error 1-95% CI u-95% CI Eff.Sample Rha
```

sds(sroach1_1) 11.53 2.99 7.31 18.95 552 1.0

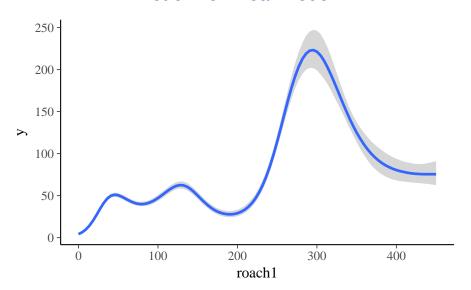
```
Population-Level Effects:
        Estimate Est.Error 1-95% CI u-95% CI Eff.Sample Rhat
Intercept 2.96 0.02 2.91 3.01 2948 1.00
```

treatment -0.66 0.02 -0.71 -0.62 2341 1.00

sroach1_1 3.48 0.15 3.20 3.77 1832 1.00 Samples were drawn using sampling (NUTS). For each parameter, Eff.

is a crude measure of effective sample size, and Rhat is the poten scale Ben Goodrick on factor of Advanced Hierarchical Models (at convergence Star Romat 14/18)

Plot of Nonlinear Model



Using **brms** to Generate Stan Programs

```
str(make_standata(y ~ s(roach1) + treatment,
                data = roaches, family = poisson),
   give.attr = FALSE)
## List of 8
## $ N : int 262
## $ Y : int [1:262(1d)] 153 127 7 7 0 0 73 24 2 2 ...
## $ nb_1 : int 1
## $ knots_1 : int [1(1d)] 8
## $ Zs_1_1 : num [1:262, 1:8] 0.0427 0.07292 -0.00439 -0.005
## $ K : int 3
## $ X : num [1:262, 1:3] 1 1 1 1 1 1 1 1 1 1 ...
## $ prior_only: int 0
```

Data and Transformed Data Blocks

```
data {
 int<lower=1> N; // total number of observations
 int Y[N]; // response variable
  int<lower=1> K; // number of population-level effects
 matrix[N, K] X; // population-level design matrix
 // data of smooth s(roach1)
 int nb_1; // number of bases
 int knots 1[nb 1];
 matrix[N, knots_1[1]] Zs_1_1;
 int prior_only; // should the likelihood be ignored?
transformed data {
 int Kc = K - 1;
 matrix[N, K - 1] Xc; // centered version of X
 vector[K - 1] means_X; // column means of X before centering
 for (i in 2:K) {
   means_X[i - 1] = mean(X[, i]);
   Xc[, i - 1] = X[, i] - means X[i - 1];
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```

Remaining Blocks

```
parameters {
  vector[Kc] b; // population-level effects
  real temp_Intercept; // temporary intercept
  // parameters of smooth s(roach1)
  vector[knots_1[1]] zs_1_1;
  real<lower=0> sds 1 1;
transformed parameters {
  vector[knots_1[1]] s_1_1 = sds_1_1 * zs_1_1;
model {
  vector[N] mu = Xc * b + Zs_1_1 * s_1_1 + temp_Intercept;
  // priors including all constants
  target += student_t_lpdf(temp_Intercept | 3, 1.1, 10);
  target += normal_lpdf(zs_1_1 | 0, 1);
  target += student_t_lpdf(sds_1_1 | 3, 0, 10)
    - 1 * student_t_lccdf(0 | 3, 0, 10);
  // likelihood including all constants
  if (!prior_only) {
    target += poisson_log_lpmf(Y | mu);
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```

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